

## Corrective actions details – Set Parameter “Support 12 V CAN Bus”

- 1) Start the TEBS E Diagnostic Software and go into the parameterization option.
- 2) Go to parameter page *TEBS - ABS/RSS*.

**Roll Stability Support (RSS)**

RSS not available

RSS OFF

RSS on / single tyres

RSS on / dual tyres

**RSS parameter**

After-run steering axle

Vehicle where tilting is critical  
(e.g. Meat Hang or independent wheel suspension)

**ATTENTION:**  
Observe the specification for tyre circumference and number of pole wheel teeth. [see help]  
For RSS drawbar vehicles, we recommend using an additional axle load sensor at the e-f axle!

**Warning lamp function**

Warning lamp goes out after 2 seconds [ECE-R13]

Warning lamp goes out at v > 7 km/h

**Tyre and pole wheel**

	Number of teeth	Tyre circumference (mm)
Axle c-d	100	3250
Axle e-f	100	3250

**Service interval**

Indicate service point via lamp

Service interval: 0 km

**ECU standby time**

Stand-By time (after ignition off): 0 Hours, 0 Minutes

**CAN messages ISO 11992**

EBS23 Standard

EBS23 group bit

EBS22 no output of total axle load

RGE22 no output for single axle loads

Support 12V CAN Bus

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- 3) Select the parameter *Support of 12 V CAN BUS*.
- 4) Write to ECU and reset TEBS E.